

# COMMON FIXED POINT THEOREMS IN COMPLEX VALUED METRIC SPACE USING IMPLICIT RELATION Dr.Preeti Sengar Department of Applied Mathematics and Computational Science, SGSITS Indore (M.P.)

## Abstract:

Banach contraction principle in gives appropriate and simple conditions to establish the existence and uniqueness of a solution of an operator equation Tx = x. Later, a number of papers were devoted to the improvement and generalization of that result. Most of these results deal with the generalizations of the different contractive conditions in metric spaces. The aim of this paper is to prove the existence and uniqueness of a common fixed point for a pair of mappings satisfying occasionally weakly compatible maps in complex valued metric space using implicit relations. The obtained results generalize and extend some of the well-known results in the literature.

**Keywords:** Complex metric space, weakly compatible, occasionally weakly compatible, implicit relation.

### **Introduction:**

Azam et al.[1] introduced the notion of complex valued metric spaces and established some fixed point results for a pair of mappings for contraction condition satisfying a rational expression. Though complex valued metric spaces from a special class of cone metric space, yet this idea is intended to define rational expressions which are not meaningful in cone metric spaces and thus many results of analysis cannot be generalized to cone metric spaces. Indeed the definition of a cone metric space banks on the underlying Banach space which is not a division ring. However, in complex valued metric spaces, one can study improvements of a host of result of analysis involving division. One can refer related results in [3, 7]. Jungck generalized the concept of weak commuting mapping given by Sessa [12], by introducing the concept of compatible mapping in different. Many authors [2, 5, 6] proved fixed point theorems for compatible mappings in different types.

In this paper, we introduced some new common fixed point theorems for generalized contractive maps in complex-valued metric space by using these new properties.

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For the sake of completeness, we recall some definitions and known results in complex valued metric space.

### **BASIC DEFINATIONS AND PRELIMINARIES**

An ordinary metric d is a real- valued function from a set  $X \times X$  into R. where X is a non-empty set. That is  $\rho : X \times X \to R$ . A Complex number  $z \in C$  is an ordered pair of real number, whose first co-ordinate is called, Re(z) and second co-ordinate is Im(z). Thus a complex-valued metric d would be a function from a set  $X \times X$  into C, where X is a non-empty set and C is the set of complex number. That is  $\rho : X \times X \to R$ .

Suppose  $\mathbb{C}$  be the set of complex numbers throughout this section and  $z_1, z_2 \in \mathbb{C}$ , recall a natural partial order relation $\leq$  on  $\mathbb{C}$  as follows:  $z_1 \leq z_2$  if and only if  $\operatorname{Re}(z_1) \leq \operatorname{Re}(z_2)$  and  $\operatorname{Im}(z_1) \leq \operatorname{Im}(z_2)$ , Consequently, one can infer that  $z_1 \leq z_2$  if one of the following conditions is satisfied:

- (i)  $\operatorname{Re}(z_1) = \operatorname{Re}(z_2), \operatorname{Im}(z_1) < (z_2)$
- (ii)  $\operatorname{Re}(z_1) < \operatorname{Re}(z_2), \operatorname{Im}(z_1) = (z_2)$
- (iii)  $\operatorname{Re}(z_1) < \operatorname{Re}(z_2), \operatorname{Im}(z_1) < (z_2)$
- (iv)  $\text{Re}(z_1) = \text{Re}(z_2), \text{Im}(z_1) = (z_2)$

In particular, we write  $z_1$  not  $\leq z_2$  if  $z_1 \neq z_2$  and one of (i), (ii), and (iii) is satisfied and we write  $z_1 < z_2$  if only (iii) is satisfied. Notice that  $0 \leq z_1$  not  $\leq z_2 \Rightarrow |z_1| < |z_2|$ , and  $z_1 \leq z_2, z_2 < z_3 \Rightarrow z_1 < z_3$ .

**Definition 2.1.** [1]. Let X be a nonempty set, whereas  $\mathbb{C}$  be the set of complex numbers. Suppose that the mapping d:X×X→  $\mathbb{C}$  satisfies the following conditions:

(C<sub>1</sub>)  $0 \leq \rho(x, y)$  for all x,y  $\in X$  and  $\rho(x,y) = 0$  if and only if x = y;

(C<sub>2</sub>)  $\rho(x, y) = \rho(y, x)$  for all x, y  $\in X$ ;

(C<sub>3</sub>)  $\rho(x,y) \leq \rho(x,z) + \rho(z,y)$  for all  $x,y,z \in X$ .

Then  $\rho$  is called a complex – valued metric on X, and  $(X,\rho)$  is called a complex- valued metric space.

**Example 2.1.** Define complex valued metric  $\rho: X \times X \to C$  by  $\rho(z_1, z_2) = e^{3i}|z_1, z_2|$ . Then  $(X, \rho)$  is a complex valued metric space.

**Definition 2.2.[1]**Let  $(X, \rho)$  be a complex valued metric space and  $B \subseteq X$ .

(i)  $b \in B$  is called an interior point of a set B whenever there is  $0 \prec r \in \mathbb{C}$  such that  $N(b, r) \subseteq B$ , where  $N(b, r) = \{y \in X : \rho(b, y) \prec r \}$ .

(ii) A point  $x \in X$  is called a limit point of B whenever for every  $0 \prec r \in \mathbb{C}$ , N(x,  $r) \cap (B \setminus \{X\}) \neq \emptyset$ .

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(iii) A subset  $A \subseteq X$  is called open whenever each element of A is an interior point of A whereas a subset  $B \subseteq X$  is called closed whenever each limit point of B belongs to B. The family  $F = \{N(x, r): x \in X, 0 \prec r\}$  is a sub-basis for a topology on X. We denote this complex topology by  $\tau_C$ . Indeed, the topology  $\tau_C$  is Hausdorff.

**Definition 2.3.[1]**Let (X, d) complex- valued metric space and  $x \in X$ . Then sequence  $\{x_n\}$  in X is

- (i) Convergent if {x<sub>n</sub>} converges to x and x is the limit point of {x<sub>n</sub>}, if for every 0 < c ∈ C, there is a natural number N such that ρ(x<sub>n</sub>,x) < c, for all n > N.We denote it by lim<sub>n→∞</sub> x<sub>n</sub> = x.
- (ii) a Cauchy sequence, if for every  $c \in C$ , with 0 < c there is a natural number N such that  $\rho(x_n, x_m) < c$ , for all n, m > N.
- (iii) The metric space  $(X, \rho)$  is a complete complex valued metric space if every Cauchy sequence is convergent.

In a metric space, every convergent sequence is a Cauchy sequence but the converse is not true. For instance, Euclidean n-space with the Euclidean distance is complete metric space where as the set of rational numbers with metric  $\rho(x,y) = |x - y|$  is not a complete metric space.

In 1968, Jungck [8] defined the concept of compatible mappings which is more general than that of commuting and weakly commuting mappings.

**Definition 2..4.[9]**A pair (f, g) of self-mappings of a metric space (X,  $\rho$ ) into itself, is called compatible mapping if  $\lim_{n\to\infty} \rho(fgx_n, gfx_n) = 0$ ) whenever  $\{x_n\}$  is a sequence in X such that  $\lim_{n\to\infty} fx_n = \lim_{n\to\infty} gx_n = z$  for some  $z \in X$ .

**Example 2.2** Let  $X = [0, \infty)$  be endowed with usual metric d and  $f, g: X \to X$  such that  $fx = x^3$  and  $gx = 2x^3$ . Then  $fgx \neq gfx$ . So, f and g are not commuting on X and |fgx - gfx| > |fx - gx|. Therefore, f and g are not weakly commuting on X. Also, for any sequence  $\{x_n\}$  in X such that  $\lim_{n\to\infty} fx_n = \lim_{n\to\infty} gx_n = u \in X$  then  $\lim_{n\to\infty} \rho(fgx_n, gfx_n) = \lim_{n\to\infty} |fgx_n - gfx_n| = 0$ . Therefore, f and g are compatible.

In 1998, Jungck and Rhoades [10] introduced the notion of weakly compatible mappings which is more general than that of compatibility as follows:

**Definition 2.5.[10]**A pair (f, g) of self-mappings of a metric space (X,  $\rho$ ) into itself, is called weakly compatible mapping if they commute at all of their coincidence point i.e. fx = gx for

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some  $x \in X$  implies fgx = gfx. Also, compatible mapping are weakly compatible but converse is not .true.

**Example 2.3.** Define complex –valued metric $\rho$ : X×X→C by such that  $\rho(z_1, z_2) = e^{ia}|z_1-z_2|$  where a is any real constant. Then(X, $\rho$ ) is a complex valued metric space .Suppose self-maps A and S be defined as:

Az =2 $e^{i\pi/4}$  if Re(z)  $\neq 0$ , Az = 3 $e^{i\pi/3}$  if Re(z) = 0, and Sz = 2 $e^{i\pi/4}$  if Re(z)  $\neq 0$ , Sz= 4 $e^{i\pi/3}$  if Re(z)=0,

Then maps A and S are weakly compatible at all  $z \in C$  with Re (z)  $\neq 0$ .

In 2008, Al Thagafi and Shahzad [2] introduced the concept of occasionally weakly compatible (owc) mappings which is a proper generalization of weakly compatible mappings.

**Definition 2.6.**[2]. Two self mappings f and g of a complex –valued metric space  $(X,\rho)$  are said to be occasionally weakly compatible (owc) if there is a point x in X which is a coincidence point of f and g at which f and g commute.

**Example 2.4.** Let  $X = [0,\infty)$  with usual metric . define f,g:X $\rightarrow$ X by fx = 2x and gx = x<sup>2</sup>, for all  $x \in X$ . Then fx = gx at x=0, 2 but fg (0) = gf(0) and fg(2)  $\neq$  gf(2). Therefore, mappings f and g are occasionally weakly compatible but not weakly compatible.

**Definition 2.7.**[11]A pair (f, g) of self – mappings of a metric space (X,  $\rho$ ) is said to be satisfy property (E.A), if here exists a sequence  $\{x_n\}$  in X such that  $\lim_{n\to\infty} fx_n = \lim_{n\to\infty} gx_n = z$  for some  $z \in X$ .

**Example 2.5.** Let  $X=[0,\infty)$ . Define f,g:  $X \to X$  by  $fx=\frac{2x}{4}$  and  $gx=\frac{5x}{4}$ , for all  $x \in X$ . Consider the sequence  $\{x_n\} = \frac{2}{n}$  clearly,  $\lim_{n\to\infty} fx_n = \lim_{n\to\infty} gx_n = 0 \in X$ . Then f and g satisfy property (E.A). **Example 2.6.** Let X = C and d be any complex valued metric .Define self maps A and S by Az = 1-z and Sz = 1+z, for all  $z \in X$ . Consider a sequence in X as  $\{x_n\} = \{1/n\}$  where n = 1, 2, 3, ... then  $\lim_{n\to\infty} Ax_n = \lim_{n\to\infty} Sx_n = 0$ .

Hence the pair (A, S) satisfies property (E.A) for the sequences  $\{x_n\}$  in X.

**Definition 2.8.[11].** Two pairs of self-maps (A, S) and (B, T) on a complex valued metric space  $(X,\rho)$  Satisfies common property (E.A) if there exists two sequences  $\{x_n\}$  and  $\{y_n\}$  in X such that

 $\lim_{n\to\infty}Ax_n = \lim_{n\to\infty}Sx_n = \lim_{n\to\infty}Ty_n = \lim_{n\to\infty}By_n = p \text{ for some } p \in X.$ 

**Definition 2.1.9.[11].** Two finite families of self maps  $\{A_i\}_{i=1}^m$  and  $\{B_j\}_{j=1}^m$  on a set X are pair wise commuting if

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- (i)  $A_i A_i = A_i A_i, i, j \in \{1, 2, 3, ..., m\},\$
- (ii)  $B_i B_j = B_j A_i, i, j \in \{1, 2, 3, \dots n\},\$

Implicit relations play important role in establishing of common fixed point results.

Let  $M_6$  be the set of all continuous functions satisfying the following conditions:

(A) 
$$\emptyset(u, 0, u, 0, 0, u) \leq 0 \Longrightarrow u \leq 0$$
  
(B)  $\emptyset(u, 0, 0, u, u, 0) \leq 0 \Longrightarrow u \leq 0$ 

(C)  $\emptyset(u, u, 0, 0, u, u) \leq 0 \Longrightarrow u \leq 0$  for all  $0 \leq u$ .

**Example 3.1.** Define  $\emptyset$ : (C)<sup>6</sup> $\rightarrow$ C as  $\emptyset$  (t<sub>1</sub>, t<sub>2</sub>, t<sub>3</sub>, t<sub>4</sub>, t<sub>5</sub>, t<sub>6</sub>) = t<sub>1</sub> –  $\emptyset_1$  (min {t<sub>2</sub>, t<sub>3</sub>, t<sub>4</sub>, t<sub>5</sub>, t<sub>6</sub>}), where  $\varphi_1$ : C $\rightarrow$ C is increasing and continuous function such that  $\emptyset_1(s) > s$  for all  $s \in C$ , clearly, $\emptyset$  satisfies all conditions (A), (B) and (C). Therefore,  $\emptyset \in M_6$ .

Our main theorem runs as follows.

**Theorem 3.1.1.**Let A, B, S, T, P and Q be six self mappings of a complex-valued metric space  $(X, \rho)$  satisfying the following conditions:

- (i)  $P(X) \subseteq AB(X), Q(X) \subseteq ST(X),$
- (ii) The pair (P, AB) and (Q, ST) share the common (E.A) property.
- (iii) For any x,  $y \in X, \emptyset$  in M<sub>6</sub>.

$$\emptyset \left\{ \begin{aligned} \rho(\mathsf{Px}, \mathsf{Qy}), \rho(\mathsf{ABx}, \mathsf{STy}), \rho(\mathsf{ABx}, \mathsf{Qy}), \\ \rho(\mathsf{STy}, \mathsf{Px}), \rho(\mathsf{ABx}, \mathsf{Px}), \rho(\mathsf{STy}, \mathsf{Qy}) \end{aligned} \right\} \leq 0$$

(iv) AB = BA, ST = TS, PB = BP, SQ = QS, QT = TQ.

Then the pair (P, AB) and (Q, ST) have a point of coincidence each. Moreover A, B, S, T, P and Q have a unique common fixed point provided both the pairs (P, AB) and (Q, ST) are occasionally weakly compatible.

**Proof.** In view of (ii), there exist two sequences  $\{x_n\}$  and  $\{y_n\}$  in X such that

 $\lim_{n\to\infty} Px_n = \lim_{n\to\infty} ABx_n = \lim_{n\to\infty} By_n = \lim_{n\to\infty} STy_n = z$  for some  $z \in X$ . since  $P(X) \subset AB(X)$ , there exist a point  $u \in X$  such that ABu = z. Put x = u and  $y = y_n$  in (iii), we have

$$\emptyset \begin{cases} \rho(\operatorname{Pu}, \operatorname{Qy}_n), \rho(\operatorname{ABu}, \operatorname{STy}_n), \rho(\operatorname{ABu}, \operatorname{Qy}_n), \\ \rho(\operatorname{STy}_n, \operatorname{Pu}), \rho(\operatorname{ABu}, \operatorname{Pu}), \rho(\operatorname{STy}_n, \operatorname{Qy}_n) \end{cases} \leq 0$$
$$\emptyset \begin{cases} \rho(\operatorname{Pu}, z), \rho(z, z), \rho(z, z), \\ \rho(z, \operatorname{Pu}), \rho(z, \operatorname{Pu}), \rho(z, z) \end{cases} \leq 0$$
$$\emptyset \begin{cases} \rho(\operatorname{Pu}, z), 0, 0, \\ \rho(z, \operatorname{Pu}), \rho(z, \operatorname{Pu}), 0 \end{cases} \leq 0$$

Using implicit relation (B), we get

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This gives Pu = z. Therefore Pu = Abu = z.

Since since  $Q(X) \subset ST(X)$ , there exist a point  $v \in X$  such that STv = z.

Put x = u and y = v in (iii), we have

$$\emptyset \begin{cases} \rho(\operatorname{Pu}, \operatorname{Q} v), \rho(\operatorname{ABu}, \operatorname{ST} v), \rho(\operatorname{ABu}, \operatorname{Q} v), \\ \rho(\operatorname{ST} v, \operatorname{Pu}), \rho(\operatorname{ABu}, \operatorname{Pu}), \rho(\operatorname{ST} v, \operatorname{Q} v) \end{cases} \leq 0$$

$$\emptyset \begin{cases} \rho(z, \operatorname{Q} v), \rho(z, z), \rho(z, \operatorname{Q} v), \\ \rho(z, z), \rho(z, z), \rho(z, \operatorname{Q} v) \end{cases} \leq 0$$

$$\emptyset \begin{cases} \rho(z, \operatorname{Q} v), 0, \rho(z, \operatorname{Q} v), \\ 0, 0, \rho(z, \operatorname{Q} v) \end{cases} \leq 0$$

Using implicit relation (A), we get

 $\rho(z, Qv) \leq 0.$ 

This gives Qv = z. Therefore Qv = ABu = Pu = STv = z.

Since (P, AB) is occasionally weakly compatible therefore Pu = ABu implies that PABu = ABPu that is Pz = ABz

Now we show that z is a fixed point of P so we put x=z and y=v in (iii), we get

$$\emptyset \begin{cases} \rho(\mathrm{Pz}, \mathrm{Q}v), \rho(\mathrm{ABz}, \mathrm{ST}v), \rho(\mathrm{ABz}, \mathrm{Q}v), \\ \rho(\mathrm{ST}v, \mathrm{Pz}), \rho(\mathrm{ABz}, \mathrm{Pz}), \rho(\mathrm{ST}z, \mathrm{Q}z) \end{cases} \leq 0$$

$$\emptyset \begin{cases} \rho(\mathrm{Pz}, \mathrm{z}), \rho(\mathrm{z}, \mathrm{z}), \rho(\mathrm{z}, \mathrm{z}), \\ \rho(\mathrm{z}, \mathrm{Pz}), \rho(\mathrm{z}, \mathrm{Pz}), \rho(\mathrm{z}, \mathrm{z}) \end{cases} \leq 0$$

$$\emptyset \begin{cases} \rho(\mathrm{Pz}, \mathrm{z}), \rho(\mathrm{z}, \mathrm{Pz}), \rho(\mathrm{z}, \mathrm{Pz}), \varphi(\mathrm{z}, \mathrm{z}) \end{cases} \leq 0$$

Using implicit relation (B), we get

$$\rho(z, Pz) \leq 0.$$

This gives Pz = z. Hence Pz = z = ABz.

Similarly (Q, ST) is occasionally weakly compatible we have Qz = STz = z.

Now we show that Bz = z.

Put x = Bz and  $y = y_n$  in (iii), we have

$$\emptyset \begin{cases} \rho(\text{PBz}, \text{Q}y_n), \rho(\text{ABBz}, \text{ST}y_n), \rho(\text{ABBz}, \text{Q}y_n), \\ \rho(\text{ST}y_n, \text{PBz}), \rho(\text{ABBz}, \text{PBz}), \rho(\text{ST}y_n, \text{Q}y_n) \end{cases} \leq 0$$

$$\emptyset \begin{cases} \rho(\text{Bz}, z), \rho(\text{Bz}, z), \rho(\text{Bz}, z), \\ \rho(z, \text{Bz}), \rho(\text{Bz}, \text{Bz}), \rho(z, z) \end{cases} \leq 0$$

$$\emptyset \begin{cases} \rho(\text{Bz}, z), \rho(\text{Bz}, z), \rho(\text{Bz}, z), \\ \rho(z, \text{Bz}), 0, 0 \end{cases} \leq 0$$

Using implicit relation (B), we get

$$\rho(z, Bz) \leq 0.$$

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This gives Bz = z.

Since ABz = z therefore Pz = ABz = Bz = Qz = STz = z

Finally we show that Tz = z.

Put x = z and y = Tz in (iii), we get

$$\begin{split} & \emptyset \begin{cases} \rho(\mathrm{Pz}, \mathrm{Q}Tz), \rho(\mathrm{ABz}, \mathrm{S}TTz), \rho(\mathrm{ABz}, \mathrm{Q}Tz), \\ \rho(\mathrm{S}TTz, \mathrm{Pz}), \rho(\mathrm{ABz}, \mathrm{Pz}), \rho(\mathrm{S}TTz, \mathrm{Q}Tz) \end{cases} \leqslant 0 \\ & \emptyset \begin{cases} \rho(z, Tz), \rho(z, Tz), \rho(z, Tz), \\ \rho(Tz, z), \rho(z, z), \rho(Tz, Tz) \end{cases} \leqslant 0 \\ & \emptyset \begin{cases} \rho(z, Tz), \rho(z, Tz), \rho(z, Tz), 0, \\ 0, \rho(z, Tz), \rho(z, Tz) \end{cases} \leqslant 0 \end{split}$$

Using implicit relation (B), we get

$$\rho(z, Tz) \leq 0.$$

This gives Tz = z.

Hence ABz = Bz = STz = Tz = Pz = Qz = z. Uniqueness follows easily.

If we put B = T = I, identity map on X, in Theorem 3.1, we have the following:

**Corollary 3.1.**Let A, S, P and Q is six self mappings of a complex-valued metric space  $(X,\rho)$  satisfying the following conditions:

- (i)  $P(X) \subseteq A(X), Q(X) \subseteq S(X),$
- (ii) The pair (P, A) and (Q, S) share the common (E.A) property.
- (iii) For any  $x, y \in X$ ,  $\emptyset$  in M<sub>6</sub>.

$$\emptyset \begin{cases} \rho(\mathsf{Px}, \mathsf{Qy}), \rho(\mathsf{Ax}, \mathsf{Sy}), \rho(\mathsf{Ax}, \mathsf{Qy}), \\ \rho(\mathsf{Sy}, \mathsf{Px}), \rho(\mathsf{Ax}, \mathsf{Px}), \rho(\mathsf{Sy}, \mathsf{Qy}) \end{cases} \leq 0$$

Then the pair (P, A) and (Q, S) have a point of coincidence each. Moreover A, S, P and Q have a unique common fixed point provided both the pairs (P, A) and (Q, S) are occasionally weakly compatible.

As an application of the theorem 3.2., we prove a common fixed point theorem for six finite families of maps on metric space, while proving our results; we utilize definitions of finite families which is natural extension of commutativity condition to two finite families.

**Theorem3.2.** Let  $\{A_1, A_2, ..., A_m\}$ ,  $\{B_1, B_2, ..., B_n\}$ ,  $\{S_1, S_2, ..., S_p\}$ ,  $\{T_1, T_2, ..., T_q\}$ ,  $\{P_1, P_2, ..., P_r\}$ , and  $\{Q_1, Q_2, ..., Q_s\}$  be six finite families of self maps of a complex – valued metric space (x, d) such that  $A = A_1, A_2, ..., A_m, B = B_1, B_2, ..., B_n$ ,  $S = S_1, S_2, ..., S_p, T = T_1, T_2, ..., T_q$ ,  $P = P_1, P_2, ..., P_r$  and  $Q = Q_1, Q_2, ..., Q_t$  satisfy the following conditions.

(1)  $P(X) \subset AB(X)(or Q \subset ST(X))$ 

(2) The pair (P, AB) (or (Q, ST)) satisfy property (E.A).

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Then the pairs (P, AB) and (Q, ST) have a point of coincidence each .Moreover finite families of self maps  $P_r$ ,  $A_iB_n$  and  $Q_t$ ,  $S_P$ ,  $T_q$  have a unique common fixed point provided that the pairs of families ({ $P_r$ }, { $A_I$ }, { $B_n$ } and { $Q_t$ }, { $S_P$ }, { $T_q$ } commute pair-wise for all i = 1, 2, ..., m, k = 1, 2, ..., n, t = 1, 2, ..., n,

**Proof.**Since self maps A,B,S,T,P and Q satisfy all the conditions of above theorem, the pairs(P,AB) and (Q,ST) have a point of coincidence. Also the pairs of families ( $\{P_r\}, \{A_iB_n\}$ ), and ( $\{Q_t\}, \{S_pT_q\}$ ) commute pair wise, we first show that PAB = ABP as

$$PAB = (P_1P_2 \dots P_r)(A_1A_2 \dots A_m)(B_1B_2 \dots B_n) = (P_1P_2 \dots P_{r-1})(A_1A_2 \dots A_m)(B_1B_2 \dots B_n)$$
  
=  $(P_1P_2 \dots P_{r-2})(A_1A_2 \dots A_mB_1B_2 \dots B_nP_{r-1}P_r) = \dots = P_1(A_1A_2 \dots A_mB_1B_2 \dots B_nP_2 \dots P_r)$   
=  $(A_1A_2 \dots A_m)(B_1B_2 \dots B_n)(P_1P_2 \dots P_r) = ABP$ 

Similarly one can prove that QST=STQ. Hence, obviously the pair (P, AB) and (Q, ST) are occasionally weakly compatible. We conclude that A, B, S, T, P and Q have a unique common fixed point in X, say z.

Now, one needs to prove that z remains the fixed point of all the component maps.

For this consider

$$A (A_{i}z) = ((A_{1}A_{2} \dots A_{m})A_{i})z = ((A_{1}A_{2} \dots A_{m-1})A_{m}A_{i})z$$
  
=  $(A_{1}A_{2} \dots A_{m-1})(A_{i}A_{m})z = (A_{1}A_{2} \dots A_{m-2})(A_{i}A_{m}A_{m-1})z$   
=  $(A_{1}A_{2} \dots A_{m-2})(A_{i}A_{m-1}A_{m})z = \dots = A_{1}(A_{1}A_{2} \dots A_{m})z$   
=  $(A_{1}A_{i})(A_{2} \dots A_{m})z$   
=  $(A_{i}A_{1})(A_{2} \dots A_{m})z = A_{i}(A_{1}A_{2} \dots A_{m})z = A_{i}Z.$ 

Similarly, one can prove that

$$P(B_{k}z) = B_{k}(Pz) = B_{k}z, B(B_{k}z) = B_{k}(Bz) = B_{k}z,$$

$$P(P_{v}z) = P_{v}(Pz) = P_{v}z$$

$$P(A_{i}z) = A_{i}(Pz) = A_{i}z, A(A_{i}z) = A_{i}(Az) = A_{i}z$$

$$P((A_{i}B_{k})z) = (A_{i}B_{k})(Pz) = (A_{i}(B_{k}Pz)) = (A_{i}Pz) = A_{i}Pz.$$

$$Q(S_{p}z) = S_{p}(Qz) = S_{p}z, Q(T_{q}z) = T_{q}(Qz) = T_{q}z,$$

$$Q(Q_{t}z) = Q_{t}(Qz) = Q_{t}z$$

$$Q((S_{p}T_{q})z) = (S_{p}T_{q})(Qz) = (S_{p}(T_{q}Qz)) = (S_{p}Qz) = S_{p}z,$$

Which shows that (for all k, i, q, p, v and t)  $P_v z$  and  $A_i B_k z$  are other fixed point of the pair (P, AB) whereas  $Q_t z$  and  $S_p T_q z$  are other fixed point of the pair (Q, ST). As A, B, S, T, P and Q have a unique common fixed point, so, we get  $z = P_v z = A_i z = B_k z = Q_t z = S_p z = T_q z$ , for all v = 1, 2, ..., r, i = 1, 2, ..., m

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$$k=1, 2, ..., n$$
,  $t=1, 2, ..., o$   
 $p=1, 2, ..., s$   $q=1, 2, ..., x$ 

Which shows that z is a unique common fixed point of  $\{P_v\}_{v=1}^s, \{A_i\}_{i=1}^m, \{B_k\}_{k=1}^n$ , $\{Q_t\}_{t=1}^o, \{S_p\}_{p=1}^s$  and  $\{T_q\}_{q=1}^x$ .

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